Predicting Unseen Links Using Learning-based Matrix Completion

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AS-level topology is important

• AS-level topology: use nodes to represent ASes, and use edges to represent AS links



- An accurate and complete topology is beneficial for understanding, operating, and diagnosing the Internet
 - Protocol design, performance analysis, fault diagnosis, security analysis

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AS-level topology is far from complete

- Due to the distributed nature of the Internet, such a complete AS-level topology is not readily available !
- Significant efforts have been spent in deploying VPs
 - The number and coverage of the VPs are still limited
 - The AS-level topology observed from current measurement data is still far from complete

There remains a considerable amount of unseen AS links to be further revealed !

CAIDA Ark VPs (100+)

RIPE RIS VPs (in the upper tier)

RouteViews VPs (in the upper tier

How to improve topology completeness

- Opportunistically conducted measurements
 - Deploy more VPs and probe more source-destination pairs
 - Neither carefully select VP locations nor select source-destination pairs

Some candidate VP locations may provide a redundant view

Resources of VPs may be limited

X Inefficient ! Consume a lot of resources but not bring equivalent improvements

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X Inefficient ! Consume a lot of resources but not bring equivalent improvements

- Targeted measurements
 - Under the guidance of specific data sources

X Only discover specific types of unseen links due to the limitation of the data source it uses (e.g. IXP data)



How to efficiently discover more unseen Links



Our goal: predict general unseen AS links

 Use multi-source data to help predict general unseen AS links for further efficiently discover them



Making the prediction task challenging



By integrating such constraints, it is possible to obtain some implicit connectivity informatio

Problem formulation

- Our problem is to predict unseen AS links given a set of observed AS paths
- -----Observed links------Unseen links



- Develop a learning-based matrix completion method specifically for the unseen AS link prediction problem
 - Traditional completion methods have limited learning capabilities
 - Some learning-based completion methods lack valuable side-information



Learn more expressive AS latent vectors and achieve outstanding prediction performance



- There are multi-source information related to the inter-domain topology and routing
- AS side-information:

AS tier feature	AS tier feature
Traffic information features	overall traffic volume feature、traffic ratio feature
Peering policy features	the general policy feature, multiple locations requirement feature, traffic ratio requirement feature and contract requirement feature
Geographic scope feature	Geographic scope feature
AS type feature	AS type feature

• Valuable for recovering unknown AS hop counts



• Framework Design



• Model parameters (e.g. embeddings and h) can be learned from known AS hop counts

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• Framework Design



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Performance evaluation

- Datasets
 - AS paths from one BGP table observed by 1134 VPs in RouteViews and RIPE RIS
 - Collect most side-information from PeeringDB
- Evaluation Metrics
 - Root Mean Squared Error (RMSE)
 - The area under the receiver operating characteristic curve (AUC)
 - True positive rate (TPR) and false positive rate (FPR)
- Evaluation Methodology
 - AS paths observed from 85% (15%) VPs for training (testing)
 - Create 20 random train-test splits for cross-validation



Comparison with other completion methods

- Funk matrix factorization method (Funk MF)
- Nonnegative matrix factorization method (NMF)
- GMF



Fig. 3. (a) RMSE of Funk MF, NMF, GMF and SGMF on different train-test splits; (b) AUC of Funk MF, NMF, GMF, SGMF on different train-test splits

Impact of the number and distribution of known measurement VPs

- Randomly select 10%, 20%, 30%, 50%, 70% of VPs
- Select VPs in each region
 - Africa (AF), Asia-Pacific (AP), Europe (EU), Latin America (LA), and North America (NA)



of SGMF with respect to different distributions of VPs reserved for training.

Unseen link prediction results

- We choose T to be 2.94 to achieve a TPR of 70.09% and a low FPR of 12.94%
 - Bring significant topology improvements of observing 70.09% unseen links
 - Save resources of launching unnecessary measurements for finding 87.06% (1-FPR) non-links



Fig. 5. (a) The FPR and TPR of the trained SGMF model under different T; (b) The distribution of FPR and TPR of trained SGMF models under other different train-test splits with T=2.94.



Validation using different datasets

- CAIDA Ark' s IPv4 Routed /24 AS Links Dataset
- AS paths returned by Looking Glass VPs



 New AS links actually verify the existence of a large number of predicted AS links

 ✓ About 65% of the new links have been correctly predicted

Significant completeness improvements can be achieved under the guidance of the predicted AS links

Fig. 6. The number of observed AS links, new AS links and successfully predicted AS links from each dataset.



Conclusion

- Develop a learning-based matrix completion method SGMF to predict Internetscale unseen links
 - Exploits a neural network and utilizes side-information
 - Improve AS link prediction performance by 17%
 - Bring topology improvements of observing 70.09% unseen links
 - Save resources of launching unnecessary measurements for finding 87.06% non-links
- Ongoing work
 - Conduct measurements under the guidance of our predicted links to discover them
 efficiently



Thanks for your attention! Q & A

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